# Gelfand-Dikii system revisited 

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#### Abstract

By making use of the algebraic structure of the problem, we give a complete description of the topology and bifurcations of the invariant level sets for the Gelfand-Dikii system.


## Résumé

En utilisant la structure algébrique du problème, nous donnons une description complète de la topologie et des bifurcations des variétés invariantes du système de Gelfand-Dikii.

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## 1. Introduction

The Gelfand-Dikii system [6] is a canonical Hamiltonian system defined by the Hamiltonian

$$
H=-q_{1}^{4}-q_{2}^{2}+3 q_{1}^{2} q_{2}-q_{1} p_{2}^{2}-2 p_{1} p_{2} .
$$

The change of variables:

$$
\begin{equation*}
q_{1}=u+v, \quad q_{2}=u v \tag{1}
\end{equation*}
$$

separates the variables of the corresponding Hamilton-Jacobi equation and allows us to find a second integral of motion

$$
F=q_{1}^{3} q_{2}+q_{1}^{2} p_{2}^{2}+2 q_{1} p_{1} p_{2}-p_{2}^{2} q_{2}-2 q_{1} q_{2}^{2}+p_{1}^{2}
$$

which proves the complete integrability of the system [1].

The aim of this paper is to give a topological description of the real level sets $\mathcal{A}_{(h, f)}^{\mathbb{R}}=$ $\{H(q, p)=h, \quad F(q, p)=f\}$. According to the Liouville-Arnold theorem [1], each connected component of the generic level set $\mathcal{A}_{(h, f)}^{\mathbb{R}}$ is either a torus, or a cylinder if the flow is complete. We prove that, although the flow is not complete, the generic real level set $\mathcal{A}_{(h, f)}^{\mathbb{R}}$ consists of one or two cylinders. To prove our result we use the algebraic structure of the problem and the Comessati theory [2] as explained by Silhol [10].

We then describe the bifurcations of the level sets $\mathcal{A}_{(h, f)}^{\mathrm{R}}$, when the parameter $(h, f)$ passes through the bifurcation set. It turns out that the bifurcation set is just the discriminant locus of the polynomial $P(z)=z^{5}+h z+f$. As the connected components of the set $\mathcal{A}_{(h, f)}^{\mathbb{R}}$ are non-compact, Fomenko's theory [5] is not applicable; then to study the bifurcations of Liouville cylinders, we use once again the algebraic structure of the problem.

The algebraic structure of the problem was described earlier by Dimitrov [3]. We also give an independent and shorter proof of his result by making use of a construction due to Jacobi and Mumford [8]. Finally we note that the description of the topology of the Gelfand-Dikii system announced in [3] is erroneous.

The paper is organized as follows: First, we explain the algebraic structure of the problem (Section 2). In Section 3, we study the topology of general level set $\mathcal{A}_{(h, f)}^{\mathbb{P}}$. In Section 4, we find the topological bifurcations of $\mathcal{A}_{(h, f)}^{\mathbb{R}}$ as the parameter $(h, f)$ passes through the bifurcation set $B$.

## 2. Algebraic structure

Let $\mathcal{A}_{(h, f)}^{\mathbb{C}}$ be the complex affine algebraic variety defined by

$$
\mathcal{A}_{(h, f)}^{\mathbb{C}}=\left\{\left(q_{1}, q_{2}, p_{1}, p_{2}\right) \in \mathbb{C}^{4}: H=h, F=f\right\}
$$

The Hamiltonian system corresponding to Gelfand-Dikii Hamiltonian reads:

$$
\begin{align*}
& \dot{q}_{1}=-2 p_{2}, \quad \dot{p}_{1}=4 q_{1}^{3}-6 q_{1} q_{2}+p_{2}^{2} \\
& \dot{q}_{2}=-2 p_{1}-2 q_{1} p_{2}, \quad \dot{p}_{2}=2 q_{2}-3 q_{1}^{2} \tag{2}
\end{align*}
$$

On $\mathcal{A}_{(h, f)}^{\mathbb{C}}$, according to (1), we obtain after some algebraic manipulations:

$$
\begin{equation*}
p_{1}=\frac{u \sqrt{P(u)}-v \sqrt{P(v)}}{u-v}, \quad p_{2}=-\frac{\sqrt{P(u)}-\sqrt{P(v)}}{u-v}, \tag{3}
\end{equation*}
$$

where

$$
P(z)=z^{5}+h z+f
$$

A straightforward computation shows that the Hamilton-Jacobi equation separates in these ( $u, v$ )-coordinates and moreover (2) is equivalent to the Jacobi inversion problem:

$$
\begin{equation*}
\frac{\mathrm{d} u}{\sqrt{P(u)}}+\frac{\mathrm{d} v}{\sqrt{P(v)}}=0, \quad \frac{u \mathrm{~d} u}{\sqrt{P(u)}}+\frac{v \mathrm{~d} v}{\sqrt{P(v)}}=2 \mathrm{~d} t \tag{4}
\end{equation*}
$$

In a similar way, one computes that the system:

$$
\begin{aligned}
& \dot{q_{1}}=2 q_{1} p_{2}+2 p_{1}, \quad \dot{q_{2}}=2 p_{2} q_{1}^{2}+2 q_{1} p_{1}-2 p_{2} q_{2}, \\
& \dot{p_{1}}=-3 q_{1}^{2} q_{2}-2 q_{1} p_{2}^{2}-2 p_{1} p_{2}+2 q_{2}^{2}, \quad \dot{p_{2}}=-q_{1}^{3}+p_{2}^{2}+4 q_{1} q_{2}
\end{aligned}
$$

associated with the second integral $F$ is equivalent to:

$$
\begin{equation*}
\frac{\mathrm{d} u}{\sqrt{P(u)}}+\frac{\mathrm{d} v}{\sqrt{P(v)}}=2 \mathrm{~d} t, \quad \frac{u \mathrm{~d} u}{\sqrt{P(u)}}+\frac{v \mathrm{~d} v}{\sqrt{P(v)}}=0 . \tag{5}
\end{equation*}
$$

Let $\Gamma$ be the hyperelliptic curve defined by

$$
\left\{w^{2}=P(z)\right\}
$$

and let $\left(w_{1}, w_{2}\right)$ be a canonical basis of holomorphic differentials on $\Gamma$ :

$$
w_{1}=\frac{a_{1} z+b_{1}}{\sqrt{P(z)}} \mathrm{d} z, \quad w_{2}=\frac{a_{2} z+b_{2}}{\sqrt{P(z)}} \mathrm{d} z
$$

The Abel-Jacobi map is defined by

$$
\begin{aligned}
\zeta: \Gamma^{(2)} & \longrightarrow \operatorname{Jac}(\Gamma) \\
P_{1}+P_{2} & \mapsto\left(\int_{P_{0}}^{P_{1}} w_{1}+\int_{P_{0}}^{P_{2}} w_{1} ; \int_{P_{0}}^{P_{1}} w_{2}+\int_{P_{0}}^{P_{2}} w_{2}\right)
\end{aligned}
$$

where $\operatorname{Jac}(\Gamma)$ is the Jacobi variety of $\Gamma, P_{0}$ is a fixed base point on $\Gamma$, and $\Gamma^{(2)}$ the symmetric product of $\Gamma$.

Solving the Jacobi inversion problem, we may express $u+v$ and $u v$ in terms of genus-two hyperelliptic theta functions associated with $\Gamma[3,4]$.

Theorem 2.1 (see [3]).
(1) If $(f / 4)^{4}+(h / 5)^{5} \neq 0$ then the affine algebraic variety $\mathcal{A}_{(h, f)}^{\mathbb{C}}$ is a smooth complex manifold isomorphic to $\operatorname{Jac}(\Gamma) \backslash D_{\infty}$ where $D_{\infty}$ is a genus-two hyperelliptic curve.
(2) The Hamiltonian flows defined by $H$ and $F$ on $\mathcal{A}_{(h, f)}^{\mathbb{C}}$ extend biholomorphically to flows on $\operatorname{Jac}(\Gamma)$ which are straight-line motions.

Proof. Consider the polynomial $f(z)$ defined by

$$
f(z)=z^{5}+h z+f
$$

and $U, V, W$ the Jacobi polynomials [8] associated with $\Gamma$ :

$$
\begin{aligned}
& U(z)=(z-u)(z-v), \quad V(z)=\frac{\sqrt{f(u)}(z-v)-\sqrt{f(v)}(z-u)}{u-v} \\
& W(z)=\frac{f(z)-V(z)^{2}}{U(z)} .
\end{aligned}
$$

After some calculations we obtain:

$$
\begin{aligned}
& U(z)=z^{2}-q_{1} z+q_{2}, \quad V(z)=-p_{2} z+\left(q_{1} p_{2}+p_{1}\right), \\
& W(z)=z^{3}+q_{1} z^{2}+\left(q_{1}^{2}-q_{2}\right) z+\left(q_{1}^{3}-2 q_{1} q_{2}-p_{2}^{2}\right) .
\end{aligned}
$$

Obviously,

$$
\begin{aligned}
\mathcal{A}_{(h, f)}^{\mathbb{C}} & =\left\{\left(q_{1}, q_{2}, p_{1}, p_{2}\right) \in \mathbb{C}^{4}: H=h ; F=f\right\} \\
& =\left\{(U, V, W) \in \mathbb{C}^{7}: f(z)-V(z)^{2}=U(z) W(z)\right\} .
\end{aligned}
$$

According to $[8$, Theorem 1.3, p.3.21], the latter is a smooth manifold if $f(z)$ has no double zero. Since, for $(f / 4)^{4}+(h / 5)^{5} \neq 0, f(z)$ has no double zero, then $\mathcal{A}_{(h, f)}^{\mathbb{C}}$ is smooth. Further $\mathcal{A}_{(h, f)}^{\mathbb{C}}=\operatorname{Jac}(\Gamma) \backslash D_{\infty}\left[8\right.$, Theorem 10.1, p.3.157], $D_{\infty}$ is a translation of the divisor $\Theta$ and by Riemann's theorem:

$$
D_{\infty}=\Theta+k=\zeta(\Gamma)+\zeta\left(P_{\infty}\right)
$$

We shall suppose that $P_{0}=P_{\infty}$, i.e. $\zeta\left(P_{\infty}\right)=0$.
We notice that $D_{\infty}$ is the image by the Abel-Jacobi map of the set $F \subset \Gamma^{(2)}$ such that

$$
F=\left\{P_{\infty}+P: P \in \Gamma\right\} \cup\{P+\tau(P): P \in \Gamma\} .
$$

$\tau$ is the hyperelliptic involution on $\Gamma$ given by

$$
\tau(z, w)=(z,-w) .
$$

It follows that

$$
\begin{equation*}
\operatorname{Jac}(\Gamma) \backslash \zeta(\Gamma) \cong \Gamma^{(2)} \backslash F \tag{6}
\end{equation*}
$$

At last, condition (2) follows from Eqs.(4) and (5). The theorem is proved.

## 3. Topological analysis

In this section we consider (2) as a system of real differential equations and we give the topological type of the real variety

$$
\mathcal{A}_{(h, f)}^{\mathbb{R}}=\left\{\left(q_{1}, q_{2}, p_{1}, p_{2}\right) \in \mathbb{R}^{4} ; H=h, F=f\right\} \quad \text { for }(h, f) \in \mathbb{R}^{2} \backslash B,
$$

where

$$
B=\left\{(h, f) \in \mathbb{R}^{2}:(h / 5)^{5}+(f / 4)^{4}=0\right\} .
$$

Definition 3.1. Let $M$ be a complex algebraic variety ( $M$ can be an algebraic curve). A real structure on $M$ is defined by an anti-holomorphic involution $S$. We denote this structure by ( $M, S$ ). The fixed points of $M$ under the action of $S$ are the real part of $M$ which will be denoted $M(\mathbb{R})$.

Definition 3.2. Let ( $M, S$ ) and ( $M^{\prime}, S^{\prime}$ ) be two real structures. We will say that these real structures are real isomorphic if there exists an isomorphism $\varphi: M \longrightarrow M^{\prime}$ such that $S=\varphi^{-1} \circ S^{\prime} \circ \varphi$.

Notice that if $(M, S)$ and $\left(M^{\prime}, S^{\prime}\right)$ are real isomorphic then $M(\mathbb{R})$ and $M^{\prime}(\mathbb{R})$ are isomorphic.

We will use the following theorem due to Comessatti.
Theorem 3.1. Let $C$ be an algebraic curve of genus $g$.
(a) If the real part of $C, C(\mathbb{R})$, has $r$ connected components, then the real part $\operatorname{Jac}(C)(\mathbb{R})$ of the Jacobi variety of $C, \operatorname{Jac}(C)$, is such that

$$
\operatorname{Jac}(C))(\mathbb{R}) \cong(\mathbb{R} / \mathbb{Z})^{g} \times(\mathbb{Z} / 2)^{r-1}
$$

(b) If $C(\mathbb{R})=\emptyset$ and
(1) if $g$ is even then

$$
\operatorname{Jac}(C)(\mathbb{R}) \cong(\mathbb{R} / \mathbb{Z})^{g},
$$

(2) if $g$ is odd then

$$
\operatorname{Jac}(C)(\mathbb{R}) \cong(\mathbb{R} / \mathbb{Z})^{g} \times(\mathbb{Z} / 2)
$$

In other words, the number of connected components of $\operatorname{Jac}(C)(\mathbb{R})$ is 1 or 2 or $2^{r-1}$.
Proof. See $[2,10]$.
Let $S$ be the involution on $\mathcal{A}_{(h, f)}^{\mathbb{C}}$ defined by

$$
\begin{align*}
S: \mathcal{A}_{(h, f)}^{\mathbb{C}} & \longrightarrow \mathcal{A}_{(h, f)}^{\mathbb{C}}  \tag{7}\\
\left(q_{1}, q_{2}, p_{1}, p_{2}\right) & \mapsto\left(\overline{q_{1}}, \overline{q_{2}}, \overline{p_{1}}, \overline{p_{2}}\right) .
\end{align*}
$$

$S$ coincides with the complex conjugation on $\mathbb{C}^{4}$ and gives a real structure on $\mathcal{A}_{(h, f)}^{\mathbb{C}}$ :

$$
\begin{align*}
\mathcal{A}_{(h, f)}^{\mathbb{C}}(\mathbb{R}) & =\mathcal{A}_{(h, f)}^{\mathbb{R}} \\
& =\left\{\left(q_{1}, q_{2}, p_{1}, p_{2}\right) \in \mathcal{A}_{(h, f)}^{\mathbb{C}}: S\left(q_{1}, q_{2}, p_{1}, p_{2}\right)=\left(q_{1}, q_{2}, p_{1}, p_{2}\right)\right\} . \tag{8}
\end{align*}
$$

$S$ induces an involution $\sigma$ on $\operatorname{Jac}(\Gamma)$ which gives a real structure on it such that: for $\left(q_{1}, q_{2}, p_{1}, p_{2}\right) \in \mathcal{A}_{(h, f)}^{\mathbb{C}}$ parameterized by $u, v$ as in (1) and (3)

$$
\begin{equation*}
P=u+v \in \Gamma^{(2)}, \quad \sigma(\zeta(P))=\zeta(S(P)) \tag{9}
\end{equation*}
$$

Proposition 3.1. Denote by $\overline{\mathcal{A}_{(h, f)}^{\mathbb{C}}}$ the compacified of $\mathcal{A}_{(h, f)}^{\mathbb{C}}$. Then:
(1) $\left(\overline{\mathcal{A}_{(h, f)}^{\mathbb{C}}}, S\right)$ and $(\operatorname{Jac}(\Gamma), \sigma)$ are real isomorphic.
(2) (a) If $(h / 5)^{5}+(f / 4)^{4}>0$ then

$$
(\operatorname{Jac}(\Gamma))(\mathbb{R}) \cong(\mathbb{R} / \mathbb{Z})^{2},
$$

i.e. one real torus.
(b) If $(h / 5)^{5}+(f / 4)^{4}<0$ then

$$
(\operatorname{Jac}(\Gamma))(\mathbb{R}) \cong(\mathbb{R} / \mathbb{Z})^{2} \times(\mathbb{Z} / 2)
$$

i.e. two real tori.

Proof. According to Theorem 2.1, $\overline{\mathcal{A}_{(h, f)}^{\mathbb{C}}}$ is a complex abelian surface isomorphic to $\operatorname{Jac}(\Gamma)$ and it has real points for all values of $(h, f)$; then $\left(\overline{\mathcal{A}_{(h, f)}^{\mathbb{C}}}, S\right)$ is real isomorphic to $(\operatorname{Jac}(\Gamma), \sigma)$ [9, Theorem 3.1].

The second part of this theorem results from Theorem 3.1. Indeed:
(a) If $(h / 5)^{5}+(f / 4)^{4}>0, P(z)$ has one real root, $z_{0}$, and therefore, the real part of the curve $\Gamma, \Gamma(\mathbb{R})$, has one connected component on $\left[z_{0} ; \infty\right)$. Then one obtains

$$
(\operatorname{Jac}(\Gamma))(\mathbb{R}) \cong(\mathbb{R} / \mathbb{Z})^{2} \times(\mathbb{Z} / 2)^{0}
$$

(b) If $(h / 5)^{5}+(f / 4)^{4}<0$ then $P(z)$ has three simple roots: $z_{1}<z_{2}<z_{0}$, and so $\Gamma$ ( $\left.\mathbb{R}\right)$ has two connected components on $\left[z_{1}, z_{2}\right]$ and $\left[z_{0}, \infty\right)$; therefore,

$$
(\operatorname{Jac}(\Gamma))(\mathbb{R}) \cong(\mathbb{R} / \mathbb{Z})^{2} \times(\mathbb{Z} / 2)^{2-1}
$$

The proposition is proved.
Corollary 3.1. Denote by $\zeta(\Gamma)(\mathbb{R})$ the real part of $\zeta(\Gamma)$.
(a) If $(h / 5)^{5}+(f / 4)^{4}>0$ then

$$
\mathcal{A}_{(h, f)}^{\mathbb{R}} \cong(\mathbb{R} / \mathbb{Z})^{2} \backslash \zeta(\Gamma)(\mathbb{R})
$$

(b) If $(h / 5)^{5}+(f / 4)^{4}<0$ then

$$
\mathcal{A}_{(h, f)}^{\mathbb{R}} \cong\left\{(\mathbb{R} / \mathbb{Z})^{2} \times(\mathbb{Z} / 2)\right\} \backslash \zeta(\Gamma)(\mathbb{R}) .
$$

Proof. This result is a consequence of Theorem 2.1 and Proposition 3.1(1).

## Theorem 3.2.

(a) If disc $(P(z))>0$ then $\mathcal{A}_{(h, f)}^{\mathbb{R}}$ is a cylinder.
(b) If disc $(P(z))<0$ then $\mathcal{A}_{(h, f)}^{\mathbb{R}}$ is a union of two cylinders.

Proof. If $\operatorname{disc}(P(z))>0, \Gamma(\mathbb{R})$ has one connected component on $\left[z_{0} ; \infty\right)$ which we denote $\Gamma_{1}$. Let us also denote $\Gamma_{1}^{(2)}$ the symmetric product of this component, i.e.

$$
\Gamma_{1}^{(2)}=\left\{P_{1}+P_{2} \in \Gamma^{(2)}: P_{j}=\left(u_{j}, w_{j}\right), u_{j} \in\left[z_{0} ; \infty\right), \quad w_{j}^{2}=P\left(u_{j}\right), \quad j=1,2\right\}
$$

and $\Gamma_{0}^{(2)}$, the subset of $\Gamma^{(2)}$ defined by

$$
\Gamma_{0}^{(2)}=\left\{P+S(P) \in \Gamma^{(2)}: P=(u, w), \quad S(P)=(\bar{u}, \bar{w}), \quad u \in \mathbb{C} \backslash \mathbb{R}\right\}
$$

According to (1) and (3), we have

$$
P_{i}+P_{j} \in \Gamma_{1}^{(2)} \cup \Gamma_{0}^{(2)} \Longleftrightarrow S\left(P_{i}+P_{j}\right)=P_{i}+P_{j}
$$

and according to (9)

$$
\sigma\left(\zeta\left(P_{i}+P_{j}\right)\right)=\zeta\left(S\left(P_{i}+P_{j}\right)\right)=\zeta\left(P_{i}+P_{j}\right)
$$

Then by the Abel-Jacobi map

$$
\begin{equation*}
\operatorname{Jac}(\Gamma)(\mathbb{R}) \cong \Gamma_{\mathrm{I}}^{(2)} \cup \Gamma_{0}^{(2)} . \tag{10}
\end{equation*}
$$

Denote by:

$$
\begin{aligned}
& \Gamma_{1, \infty}=\left\{P+P_{\alpha} \in \Gamma^{(2)}: P \in \Gamma_{1} \text { and } P_{\alpha}=\tau(P) \text { or } P_{\alpha}=P_{\infty}\right\} \subset \Gamma^{(2)} . \\
& D_{\infty}(\mathbb{R})=\zeta\left(\Gamma_{1, \infty}\right)=\zeta\left(\Gamma_{1}\right) .
\end{aligned}
$$

Then

$$
\operatorname{Jac}(\Gamma)(\mathbb{R}) \cap D_{\infty}(\mathbb{R})=\zeta\left(\Gamma_{1}\right) .
$$

The embedding

$$
\zeta: \Gamma \hookrightarrow \operatorname{Jac}(\Gamma) \quad P \mapsto \zeta(P)
$$

induces a homomorphism

$$
\varphi: H_{1}(\Gamma, \mathbb{Z}) \longrightarrow H_{1}(\operatorname{Jac}(\Gamma), \mathbb{Z})
$$

which is in fact an isomorphism.
As $\Gamma_{1}$ represents a non-zero homology cycle on $\Gamma, \zeta\left(\Gamma_{1}\right)$ represents a non-zero homology cycle on $\operatorname{Jac}(\Gamma)$ too.

We conclude that if we remove this circle from the real torus $\operatorname{Jac}(\Gamma)(\mathbb{R})$, we obtain a cylinder.

If $\operatorname{disc}(P(z)<0$, then the real part of the curve $\Gamma, \Gamma(\mathbb{R})$, has two connected components which we denote by $\Gamma_{1}$ and $\Gamma_{2}$, respectively, on $[z 0 ; \infty)$ and $\left[z_{1} ; z_{2}\right]$.

According to Abel-Jacobi map, formulas (1),(3), and the remark mentioned above we have

$$
\begin{equation*}
\operatorname{Jac}(\Gamma)(\mathbb{R}) \cong \underbrace{\left(\Gamma_{1} \times \Gamma_{2}\right)}_{T_{1}}+\underbrace{\left(\Gamma_{1}^{(2)} \cup \Gamma_{2}^{(2)} \cup \Gamma_{0}^{(2)}\right)}_{T_{2}} \tag{11}
\end{equation*}
$$

where

$$
\Gamma_{2}^{(2)}=\left\{P_{1}+P_{2} \in \Gamma^{(2)}: P_{j}=\left(u_{j}, w_{j}\right), \quad u_{j} \in\left[z_{1} ; z_{2}\right], \quad w_{j}^{2}=P\left(u_{j}\right), \quad j=1,2\right\}
$$

$T_{1}$ and $T_{2}$ have no common point because of: for $\left.z \in\right] z_{2}, z_{0}\left[\right.$, if $(u+v) \in T_{1}$ then $(z-$ $u)(z-v)<0$ and if $(u+v) \in T_{2},(z-u)(z-v)>0$.

Define:

$$
\begin{aligned}
& \Gamma_{1, \infty}=\left\{P+P_{\alpha} \in \Gamma^{(2)}: P \in \Gamma_{1} \text { and } P_{\alpha}=\tau(P) \text { or } P_{\alpha}=P_{\infty}\right\} \subset \Gamma_{1}^{(2)}, \\
& \Gamma_{2, \infty}=\left\{P+P_{\infty} \in \Gamma^{(2)}: P \in \Gamma_{2}\right\} \subset \Gamma_{1} \times \Gamma_{2} .
\end{aligned}
$$



Fig. 1.
$D_{\infty}(\mathbb{R})$ has two connected components without common point which are $\zeta\left(\Gamma_{1, \infty}\right)$ and $\zeta\left(\Gamma_{2, \infty}\right)$ :

$$
\operatorname{Jac}(\Gamma)(\mathbb{R}) \cap D_{\infty}(\mathbb{R})=\zeta\left(\Gamma_{1, \infty}\right) \cup \zeta\left(\Gamma_{2, \infty}\right)
$$

and

$$
T_{1} \cap D_{\infty}(\mathbb{R})=\zeta\left(\Gamma_{2, \infty}\right)=\zeta\left(\Gamma_{2}\right), \quad T_{2} \cap D_{\infty}(\mathbb{R})=\zeta\left(\Gamma_{1, \infty}\right)=\zeta\left(\Gamma_{1}\right) .
$$

As before, $\zeta\left(\Gamma_{1}\right)$ and $\zeta\left(\Gamma_{2}\right)$ are two circles on $\operatorname{Jac}(\Gamma)$ not homologous to zero.
We conclude that

$$
\operatorname{Jac}(\Gamma)(\mathbb{R}) \backslash \zeta(\Gamma)(\mathbb{R}) \cong\left\{T_{1} \backslash S^{1}\right\} \cup\left\{T_{2} \backslash S^{1}\right\}
$$

is a union of two cylinders. The theorem is proved.

## 4. Topological bifurcations of the varieties $\mathcal{A}_{(h, f)}^{\mathbb{P}}$

In this section we describe the topology of singular level sets $\mathcal{A}_{(h, f)}^{\mathbb{R}}$, when $(h, f) \in B$. We recall that $B$ is defined by

$$
B=\left\{(h, f) \in \mathbb{R}^{2}:(h / 5)^{5}+(f / 4)^{4}=0\right\} .
$$

We denote by $B_{1}$ and $B_{2}$ the connected components of the set $B$ corresponding, respectively, to $f>0$ and $f<0$ (Fig. 1).

If $\left(h_{0}, f_{0}\right) \in B_{1}$ then $P(z)$ has a double real root $z_{0}=z_{2}$ and a simple root $z_{1}<z_{0}$; and for $\left(h_{0}, f_{0}\right)=(0,0), \quad 0$ is a root of multiplicity 5 .

Let $L_{1}$ and $L_{0}$ denote the sets:

$$
\begin{aligned}
& L_{0}=\left\{0+P: P \in \Gamma_{1} \backslash P_{\infty} 0=(0,0)\right\} \subset \Gamma^{(2)}, \\
& L_{1}=\left\{P_{0}+P: P \in \Gamma_{1} \backslash P_{\infty} \text { and } P_{0}=\left(z_{0} ; 0\right)\right\} \subset \Gamma^{(2)},
\end{aligned}
$$

where $\Gamma_{1}$ is the only connected component of the real part of $\Gamma$ when $\left(h_{0}, f_{0}\right) \in B_{1} \cup(0,0)$ (see Figs. 2b.b and 4b.b).


Fig. 2b.

In the same way, if $\left(h_{0}, f_{0}\right) \in B_{2}, P(z)$ has a double real root $z_{1}=z_{2}$ and a simple root $z_{0}>z_{1} . L_{2}$ will represent the set

$$
L_{2}=\left\{P_{1}+P: P \in \Gamma_{1} \backslash P_{\infty} \text { and } P_{1}=\left(z_{1} ; 0\right)\right\} \subset \Gamma^{(2)}
$$

$\Gamma_{1}$ is also the connected component of the curve $\Gamma$ on $\left[z_{0} ; \infty\right)$ (See Fig. 3b.b).
Theorem 4.1. Let $\left(h_{0}, f_{0}\right) \in B$ and $\mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathbb{R}}$ be the corresponding singular level set.
(a) If $\left(h_{0}, f_{0}\right) \in B_{1} \cup\{(0,0)\}$ then $\mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathbb{R}}$ is a smooth real manifold, except in the points $\left(q_{1}, q_{2}, p_{1}, p_{2}\right)$ parameterized by $\left(u_{0}, v\right) \in L_{1}$ or $L_{0}$.

- If $\left(h_{0}, f_{0}\right) \in B_{1}, \mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathbb{R}}$ is homeomorphic to $\left(S^{1} \vee S^{1}\right) \times \mathbb{R}^{1}$ where $S^{1} \vee S^{1}$ is a union of two circles with one common point (Fig. 2a.b).
- If $\left(h_{0}, f_{0}\right)=(0,0), \mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathbb{R}}$ is a cylinder with singularities along the line $\zeta\left(L_{0}\right)$ (Fig. 4a.b).
(b) If $\left(h_{0}, f_{0}\right) \in B_{2}$ then $\mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathbb{R}}$ is a union of a cylinder and a line (Fig. 3a.b).

Proof. According to Theorem 2.1, in all the points $\left(q_{1}, q_{2}, p_{1}, p_{2}\right) \in \mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathrm{R}}$ which are not parameterized by $\left(u_{0}, v_{0}\right) \in L_{k}, k=0,1,2, \mathcal{A}_{\left(h_{0}: f_{0}\right)}^{\mathbb{R}}$ is smooth. Now, we show that $L_{0}, L_{1}$ and $L_{2}$ parameterize the singular points of $\mathcal{A}_{\left(h_{0}, f_{0}\right)}^{\mathbb{R}}$. According to (1) the Hamiltonian $H$ becomes

$$
H\left(u, v, p_{u}, p_{v}\right)=-u^{4}-u^{3} v-u^{2} v^{2}-u v^{3}-v^{4}+\frac{p_{u}^{2}}{(u-v)}-\frac{p_{v}^{2}}{(u-v)},
$$

where $p_{u}$ and $p_{v}$ are the conjugate coordinates of $u, v$.
(a)
Fig. 3a. (b)

(c)


Fig. 3b.
We also have

$$
(u-v) H=-u^{5}+v^{5}+p_{u}^{2}-p_{v}^{2}
$$

and hence

$$
F=-u H-u^{5}+p_{u}^{2}
$$

The calculation of the gradient of $F$ gives

$$
\operatorname{grad}(F)=\left\{\begin{array}{l}
\frac{\partial F}{\partial u}=-H-5 u^{4}-u \frac{\partial H}{\partial u}  \tag{12}\\
\frac{\partial F}{\partial v}=-u \frac{\partial H}{\partial v} \\
\frac{\partial F}{\partial p_{u}}=2 p_{u}-u \frac{\partial H}{\partial p_{u}} \\
\frac{\partial F}{\partial p_{v}}=-u \frac{\partial H}{\partial p_{v}}
\end{array}\right.
$$

It is obvious that if:

$$
\begin{equation*}
P^{\prime}(u)=h+5 u^{4}=0, \quad p_{u}=\frac{1}{2}(u-v) \dot{u}=0 \tag{13}
\end{equation*}
$$

then
$\operatorname{grad}(F)=-u \operatorname{grad}(H)$.
So, as in the points of $\mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathrm{R}}$ parameterized by $\left(u_{0}, v\right) \in L_{k}, k=0,1,2$, we have

$$
\begin{align*}
& P\left(u_{0}\right)=u_{0}^{5}+h u_{0}+f=0, \quad P^{\prime}\left(u_{0}\right)=h+5 u_{0}^{4}=0  \tag{14}\\
& p_{u}=\frac{1}{2}\left(u_{0}-v\right) \dot{u}_{0}=0
\end{align*}
$$



Fig. 4b.
then

$$
\operatorname{grad}(F)=-u_{0} \operatorname{grad}(H)
$$

It follows that, at these points, $\mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathbb{R}}$ is not smooth.
Let us consider the map $\mu$ defined by

$$
\begin{aligned}
\mu: \Gamma^{(2)} \backslash F & \longrightarrow \mathcal{A}_{\left(h_{0}: f_{0}\right)}^{\mathbb{R}} \\
u+v & \mapsto\left(q_{1}, q_{2}, p_{1}, p_{2}\right),
\end{aligned}
$$

where $q_{1}, q_{2}, p_{1}$ and $p_{2}$ are as in (1) and (3).
If $\left(h_{0}, f_{0}\right) \in B_{1} \cup\{(0,0)\}$,

$$
\mathcal{A}_{\left(h_{0} ; f_{0}\right)}^{\mathbb{R}} \cong\left\{\Gamma_{1}^{(2)} \cup \Gamma_{0}^{(2)}\right\} \backslash\left(\Gamma_{1, \infty}\right) .
$$

For $\left(h_{0}, f_{0}\right) \in B_{2}$ according to the map $\mu$,

$$
\mathcal{A}_{\left(h_{0}, f_{0}\right)}^{\mathbb{R}} \cong \underbrace{\left\{P_{1}\right\} \times\left\{\Gamma_{1} \backslash P_{\infty}\right\}}_{\left(L_{2}\right)}+\underbrace{\left\{\Gamma_{1}^{(2)} \cup \Gamma_{0}^{(2)}\right\} \backslash\left(\Gamma_{1, \infty}\right)}_{(C)}
$$

The theorem is proved.

Corollary 4.1. All bifurcations of connected components of the invariant manifold $\mathcal{A}_{(h . f)}^{\mathbb{R}}$ are described in Fig. 1.

Proof. Bifurcation (i): The cylinder obtained in domain (I) collapses along the axial line ( $\zeta\left(L_{1}\right)$, Theorem 4.1) before splitting into two cylinders. This bifurcation is described in Fig. 2a

Bifurcation (ii): It is the "inverse" bifurcation of the following bifurcation: one of two cylinders contracts to this axial line ( $\zeta\left(L_{1}\right)$, Theorem 4.1 ) and "vanishes". This bifurcation is described in Fig. 3a

Bifurcation (iii): The cylinder collapses along the line $\zeta\left(L_{0}\right)$ before splitting into two cylinders. This bifurcation is represented by Fig. 4a.

The corollary is proved.

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